### TMTH 204 FINAL EXAM FORMULA SHEET

## **CHAPTER 5:** Graphs

slope 
$$m = \frac{\text{rise}}{\text{run}} = \frac{y_2 - y_1}{x_2 - x_1}$$

equation 
$$y = mx + b$$

### **CHAPTER 11: Determinants**

$$\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix} = a_1 b_2 - a_2 b_1$$

$$x = \frac{\begin{vmatrix} c_1 & b_1 \\ c_2 & b_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}}, \qquad y = \frac{\begin{vmatrix} a_1 & c_1 \\ a_2 & c_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}}$$

$$y = \frac{\begin{vmatrix} a_1 & c_1 \\ a_2 & c_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}}$$

### **Third-Order Determinant:**

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = a_1 b_2 c_3 + a_3 b_1 c_2 + a_2 b_3 c_1 - a_3 b_2 c_1 - a_1 b_3 c_2 - a_2 b_1 c_3$$

### Cramer's Rule for 3 by 3 system:

$$x = \frac{\begin{vmatrix} k_1 & b_1 & c_1 \\ k_2 & b_2 & c_2 \\ k_3 & b_3 & c_3 \end{vmatrix}}{\Lambda}$$

$$y = \frac{\begin{vmatrix} a_1 & k_1 & c_1 \\ a_2 & k_2 & c_2 \\ a_3 & k_3 & c_3 \end{vmatrix}}{\Lambda}$$

$$x = \frac{\begin{vmatrix} k_1 & b_1 & c_1 \\ k_2 & b_2 & c_2 \\ k_3 & b_3 & c_3 \end{vmatrix}}{\Delta}, \qquad y = \frac{\begin{vmatrix} a_1 & k_1 & c_1 \\ a_2 & k_2 & c_2 \\ a_3 & k_3 & c_3 \end{vmatrix}}{\Delta}, \qquad z = \frac{\begin{vmatrix} a_1 & b_1 & k_1 \\ a_2 & b_2 & k_2 \\ a_3 & b_3 & k_3 \end{vmatrix}}{\Delta}, \quad \text{where } \Delta = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} \neq 0$$

## CHAPTER 12: Matrices

$$\begin{pmatrix} a & b & c \\ d & e & f \end{pmatrix} \begin{pmatrix} u & x \\ v & y \\ w & z \end{pmatrix} = \begin{pmatrix} au + bv + cw & ax + by + cz \\ du + ev + fw & dx + ey + fz \end{pmatrix}$$

$$AA^{-1} = A^{-1}A = I$$

**Solution to system of equations** 
$$AX = B$$
 is  $X = A^{-1}B$ 

$$AX = B$$

$$S X = A^{-1}I$$

# **CHAPTER 14:** Quadratic Equations

**Quadratic Formula** If 
$$ax^2 + bx + c = 0$$
 and  $a \ne 0$ , then  $x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$ 

## **CHAPTER 15:** Oblique Triangles and Vectors

$$\sin \theta = \sin(180^{\circ} - \theta)$$
  $\cos \theta = \cos(360^{\circ} - \theta)$   $\tan \theta = \tan(180^{\circ} + \theta)$ 

Law of Sines 
$$\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$$

**Law of Cosines:** 
$$a^2 = b^2 + c^2 - 2bc \cos A$$
 or  $\cos A = \frac{b^2 + c^2 - a^2}{2bc}$ 

$$b^2 = a^2 + c^2 - 2ac \cos B$$
 or  $\cos B = \frac{a^2 + c^2 - b^2}{2ac}$ 

$$c^2 = a^2 + b^2 - 2ab \cos C$$
 or  $\cos C = \frac{a^2 + b^2 - c^2}{2ab}$ 

## CHAPTER 17: Graphs of the Trigonometric Functions

**Angle Conversions** 
$$1 \text{ rev} = 360^{\circ} = 2 \pi \text{ rad}$$

Sine Wave as a Function of Time:  $y = a \sin(\omega t + \varphi)$ 

amplitude = 
$$|a|$$
 angular velocity =  $\omega$  period =  $\frac{2\pi}{\omega}$ 

frequency = 
$$\frac{\omega}{2\pi}$$
 phase angle =  $\varphi$  phase shift =  $-\frac{\varphi}{\omega}$ 

**Cosine and Sine Curves Related** 
$$\cos \theta = \sin(\theta + 90^{\circ})$$

#### Sinusoidals as Phasors:

$$a \sin(\omega t + \varphi)$$
 is identified with  $a \angle \varphi$ 

$$a\cos(\omega t + \varphi)$$
 is identified with  $a \angle (\varphi + 90^{\circ})$ 

### Addition of a Sine Wave and a Cosine Wave:

$$A \sin \omega t + B \cos \omega t = R \sin(\omega t + \varphi)$$
 where  $R = \sqrt{A^2 + B^2}$  and  $\varphi = \arctan \frac{B}{A}$ 

# **CHAPTER 18:** Trigonometric Identities and Equations

$$csc \theta = \frac{1}{\sin \theta}$$
 $sec \theta = \frac{1}{\cos \theta}$ 
 $cot \theta = \frac{1}{\tan \theta}$ 

$$\tan \theta = \frac{\sin \theta}{\cos \theta} \qquad \cot \theta = \frac{\cos \theta}{\sin \theta}$$

$$\sin^2\theta + \cos^2\theta = 1 \qquad \tan^2\theta + 1 = \sec^2\theta \qquad 1 + \cot^2\theta = \csc^2\theta$$

#### Sum and Difference Identities:

$$sin(A \pm B) = sin A cos B \pm cos A sin B$$

$$cos(A \pm B) = cos A cos B \mp sin A sin B$$

$$\tan(A \pm B) = \frac{\tan A \pm \tan B}{1 \mp \tan A \tan B}$$

### **Double Angle Identities:**

$$\sin 2A = 2 \sin A \cos A$$

$$\cos 2A = \cos^2 A - \sin^2 A$$

$$\tan 2A = \frac{2 \tan A}{1 - \tan^2 A}$$

$$\cos 2A = 1 - 2\sin^2 A$$

$$\cos 2A = 2\cos^2 A - 1$$

## **Function Values of Special Angles:**

θ		$\sin \theta$	$\cos \theta$	$\tan \theta$	$\cot \theta$	$\sec \theta$	$\csc \theta$
30°	$\frac{\pi}{6}$	$\frac{1}{2}$	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{3}}{3} \circ r \frac{1}{\sqrt{3}}$	$\sqrt{3}$	$\frac{2\sqrt{3}}{3} o r \frac{2}{\sqrt{3}}$	2
45°	$\frac{\pi}{4}$	$\frac{\sqrt{2}}{2} o r \frac{1}{\sqrt{2}}$	$\frac{\sqrt{2}}{2}  o  r \frac{1}{\sqrt{2}}$	1	1	$\sqrt{2}$	$\sqrt{2}$
60°	$\frac{\pi}{3}$	$\frac{\sqrt{3}}{2}$	$\frac{1}{2}$	$\sqrt{3}$	$\frac{\sqrt{3}}{3} \circ r \frac{1}{\sqrt{3}}$	2	$\frac{2\sqrt{3}}{3} \circ r \frac{2}{\sqrt{3}}$

# **CHAPTER 21:** Complex Numbers

The Imaginary Unit and its Powers  $j=\sqrt{-1}$  ,  $j^2=-1$ ,  $j^3=-j$ ,  $j^4=1$ ,  $j^5=j$ , ...

**Complex Number in Rectangular Form** a + jb real part = a, imaginary part = b

**Complex Number in Polar Form**  $r \angle \theta$  magnitude = r, polar angle =  $\theta$ 

**Polar to Rectangular Form**  $r \angle \theta = a + jb$ , where  $a = r \cos \theta$  and  $b = r \sin \theta$ 

**Rectangular to Polar Form**  $a + jb = \sqrt{a^2 + b^2} \angle \tan^{-1} \left(\frac{b}{a}\right)$ 

## Complex Current, Voltage, and Impedance:

Given 
$$i=I_{max}\sin(\omega t+\varphi)$$
,  $I=I_{eff} \angle \varphi$ , where  $I_{eff}=\frac{I_{max}}{\sqrt{2}}$ 

Given 
$$v=V_{max}\sin(\omega t+\varphi)$$
,  $V=V_{eff}\,\angle\varphi$ , where  $V_{eff}=\frac{V_{max}}{\sqrt{2}}$ 

$$\mathbf{Z} = R + jX = \sqrt{R^2 + X^2} \angle \varphi$$
, where  $X = X_L - X_C$  and  $\varphi = \tan^{-1}\left(\frac{X}{R}\right)$ 

Ohm's Law for AC circuits V = ZI